EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	286	(machining or welding or cutting or grinding or processing) near (tool or device or apparatus or unit or station or zone) and turning near station	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:42
L2	6269	(machining or welding or cutting or grinding or processing) near (tool or device or apparatus or unit or station or zone) and (turning near (station or unit) or turntable)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:44
L3	1305	(228/47.1,49.1,49.2).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/08/30 15:43
L5	19	3 and (machining or welding or cutting or grinding or processing) near (tool or device or apparatus or unit or station or zone) and (turning near (station or unit) or turntable)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:44
L6	11	5 and (robot or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:44
L7	6269	(2 or 3) and (machining or welding or cutting or grinding or processing) near (tool or device or apparatus or unit or station or zone) and (turning near (station or unit) or turntable)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:44
L8	796	7 and (robot or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:45

EAST Search History

L9	41	8 and (robot or robot$4) near (transport or transport$6)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:45
L10	1	9 and (robot or robot$4) near (rotary or rotation or rotate or rotat$4 or rotation$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:46
L11	46	8 and (robot or robot$4) near (rotary or rotation or rotate or rotat$4 or rotation$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:46
L12	275	8 and (robot or robot$4) near (arm or articulate or articulat$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:46
L13	9	12 and (robot or robot$4) near (arm near (articulate or articulat$4))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:47
L14	24	12 and (arm near (articulate or articulat$4))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:47
L15	22	8 and (load or weight) near (max or maximum or tolerance or capable or capability or capacity)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:48

EAST Search History

L16	271	8 and (grip or gripp$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:48
L17	1	9 and (grip or gripp$4) near (replace or replacement or replac$4 or replaceable)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:48
L18	43	16 and (grip or gripp$4) near (tool or tools or device or devices)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:49
L19	36	18 and (store or stor$4 or storage)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:49
L20	1	19 and (store or stor$4 or storage) near (grip or gripp$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:50
L21	58	8 and (weld or weld$4) near (unit or site or station or zone)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:50
L22	27	8 and (manual or hand or auto or automatic or manual$4 or automatic$4) near (feed or feed$4 or store or stor$4 or storage)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:52

L23	17	22 and (manual or hand or auto or automatic or manual$4 or automatic$4) near (feed or feed$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:52
L24	10	22 and (manual or hand or auto or automatic or manual$4 or automatic$4) near (store or stor$4 or storage)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/08/30 15:52